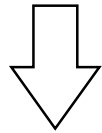


CLIPS-03

Control Techniques

By Gwo-Jen Hwang

- Game of Sticks
(poison.clp)

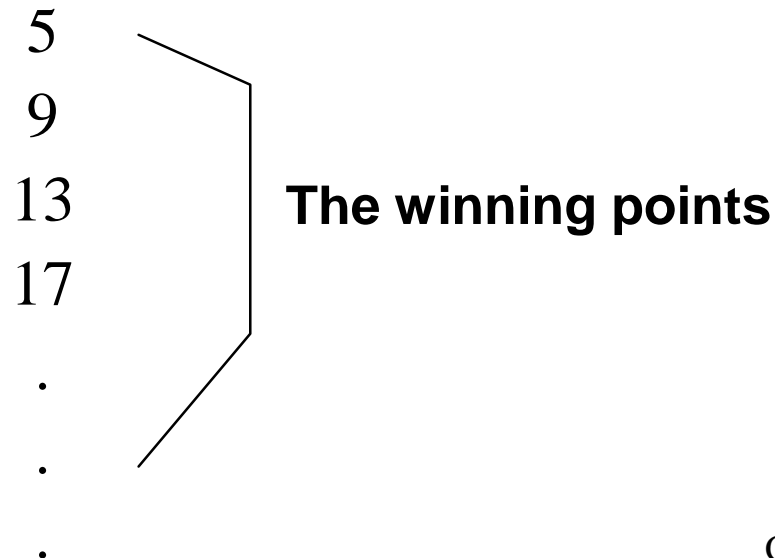


Initially, there are n sticks.

Two persons take the sticks in turn.

Each time only one to three sticks can be taken.

The one who takes the last stick loses.



```
(defrule player-select
  (phase choose-player)
=>
  (printout t "who moves first (c/h) ?")
  (assert (player-select =(READ)))
)
```

initial phase

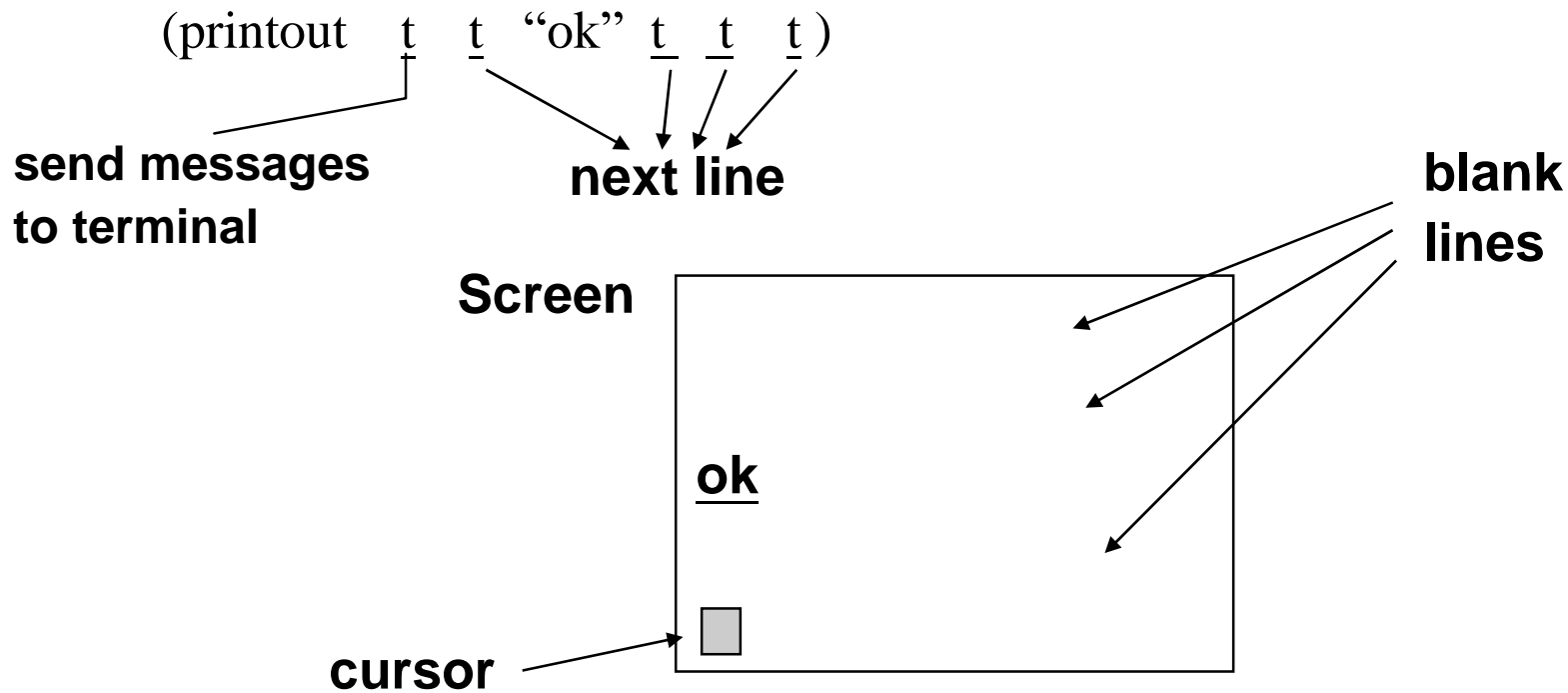
```
(defrule good-player-choice
  ?phase <- (phase choose-player)
  ?choice <- (player-select ?player&c|h)
=>
  (retract ?phase ?choice)
  (assert (player-move ?player))
)
```

**enter next phase:
start the game**

```

(defrule bad-player-choice
  ?phase <- (phase choose-player)
  ?choice <- (player-select ?player&~c&~h)
=>
  (retract ?phase ?choice)
  (assert (phase choose-player))
  (printout t "Stupid! Choose again!" crlf)
)

```



- Predicate (boolean) Functions

(p.444 ~ p.445)

NOT

AND

OR

EQ equal (any)

NEQ not equal (any)

= equal (numeric only)

!= not equal (numeric only)

>=

<=

<

>

(EQ John John) \Rightarrow T

(< 6 8) \Rightarrow T

(= 5 4) \Rightarrow F

(AND (< 4 5)
(= 6 7)) \Rightarrow F

(NOT (!= 6 5)) \Rightarrow F

numberp

stringp

wordp

integerp

evenp

oddp



type predicate

functions

(numberp 5) ⇒ T

(numberp John) ⇒ F

(stringp "ok") ⇒ T

(evenp 5) ⇒ F

```
(defrule get-human-move
  (player-move h)
  (pile-size ?size)
  (test (> ?size 1))
  =>
  (printout t "How many sticks do you want to take?")
  (assert (human-takes =(read)))
)
```

matching

test condition

```

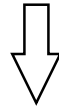
(defrule good-human-move
  ?whose-turn <- (player-move h)
  ?pile <- (pile-size ?size)
  ? number-taken <- (human-take ?choice)
  (test (and (integerp ?choice)
             (>= ?choice 1)
             (<= ?choice 3)
             (< ?choice ?size)))
  =>
  (retract ?whose-turn ?number-taken ?pile)
  (assert (pile-size =(- ?size ?choice)))
  (assert (player-move c ))
)

```

test valid moves

- Predicate field constraint ?

```
(pile-size ?size)
(test (> ?size 1))
```



```
(pile-size ?size&:(> ?size 1))
```

*only the fact which satisfies the
constraint will be matched*

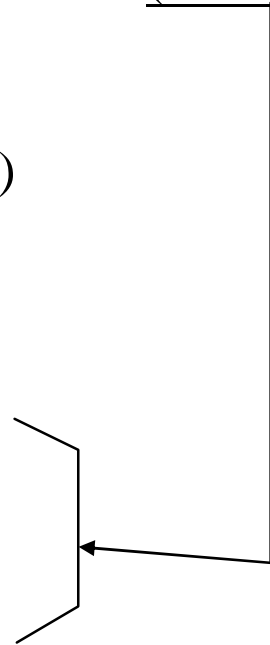
```
(defrule add-sum
  (data-item ?value&:(numberp ?value))
  ?old-total <- (total ?total)
  =>
  (retract ?old-total)
  (assert (total =(+ ?total ?value))))
)
```

- Equality Field Constraint

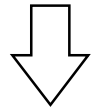
“ ”

```
(defrule computer-move
  ?whose-turn <- (player-move C)
  ?pile <- (pile-size ?size)
  (test (> ?size 1))
  (computer-take ?number sticks-remained =(mod ?size 4))
=>
  (retract ?whose-turn ?pile)
  (assert (pile-size =(- ?size ?number)))
  (assert (player-move h))
)
```

```
(computer-take 1 sticks-remained 1)
(computer-take 1 sticks-remained 2)
(computer-take 2 sticks-remained 3)
(computer-take 3 sticks-remained 0)
```

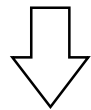


```
(defrule test
  (data length ?y)
  (data width ?x&=(+ 9 ?y) |=(- 8 ?y))
  =>
)
```



(data length 4)

```
(defrule test
  (data width ?x&9|8)
  =>
)
```



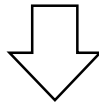
(data width 9) matched !
(data width 8) matched !

- Saliency

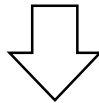
```
(defrule fire-first
  (declare (saliency 30))
  (priority first)
=>
  (printout t "print first" crlf)
)
```

$-10000 \leq \text{Saliency} \leq 10000$
default = 0

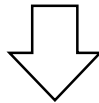
- The main advantage of a rule-based program is that
*“programmer does not have to
worry about controlling execution”*



The execution flow is fully controlled by inference engine.



*The programmer does not need to specify which rule should
be fired next.*



*Using too many “Salience” will violate this advantage and
make the expert system work like a conventional program.*

- The uses of salience

Saliency should primarily be used to determine the order of firing rules.

Saliency should NOT be used as a method of *selecting rules to fire*.

```

(defrule pick-A
  (declare (salience 10))
  ?phase <- (choose-move)
  (ready A)
=>
  (retract ?phase)
  (assert (picked A))
)

```

```

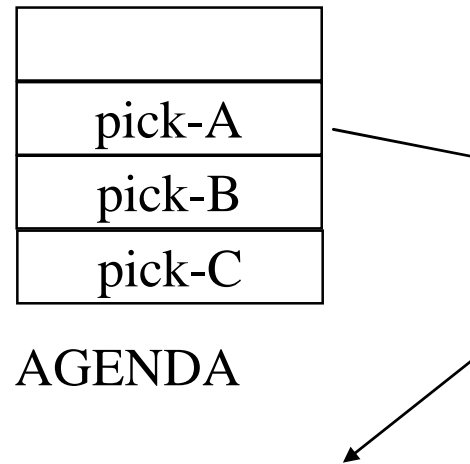
(defrule pick-B
  (declare (salience 5))
  ?phase <- (choose-move)
  (ready B)
=>
  (retract ?phase)
  (assert (picked B))
)

```

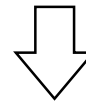
```

(defrule pick-C
  ?phase <- (choose-move)
  (ready C)
  ...

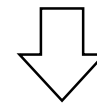
```



*If rule **pick-A** is fired, rules **pick-B** and **pick-C** will be removed from AGENDA since (choose move) is removed.*



*In this case, Saliences are used to imply if **A**, **B** and **C** are all true, choose **A** first*



BAD

A rule should be independent with any other rule.

```
(defrule pick-B
```

```
  (declare (salience 5))
```

```
  ?phase <- (choose-move)
```

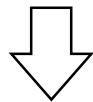
```
  (ready B)
```

```
  =>
```

```
  (retract ?phase)
```

```
  (assert (picked B))
```

```
)
```



```
(defrule pick-B
```

```
  ?phase <- (choose-move)
```

```
  (ready B)
```

```
  (not (ready A))
```

```
  =>
```

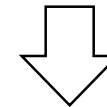
```
  (retract ?phase)
```

```
  (assert (picked B))
```

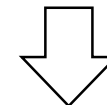
```
)
```

GOOD!

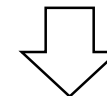
*IF both A and B are ready,
choose A.*



*The meaning of this rule is
dependent on rule **pick-A**.*

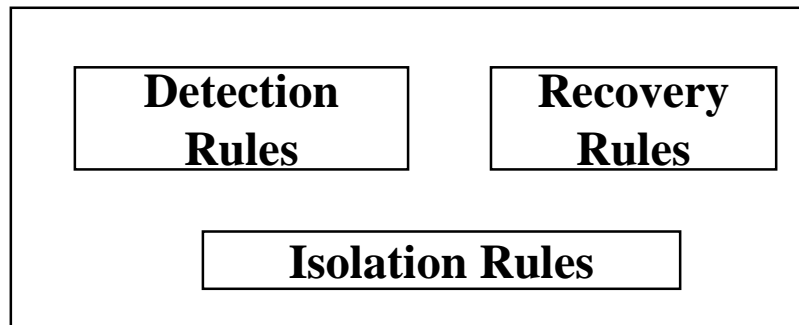
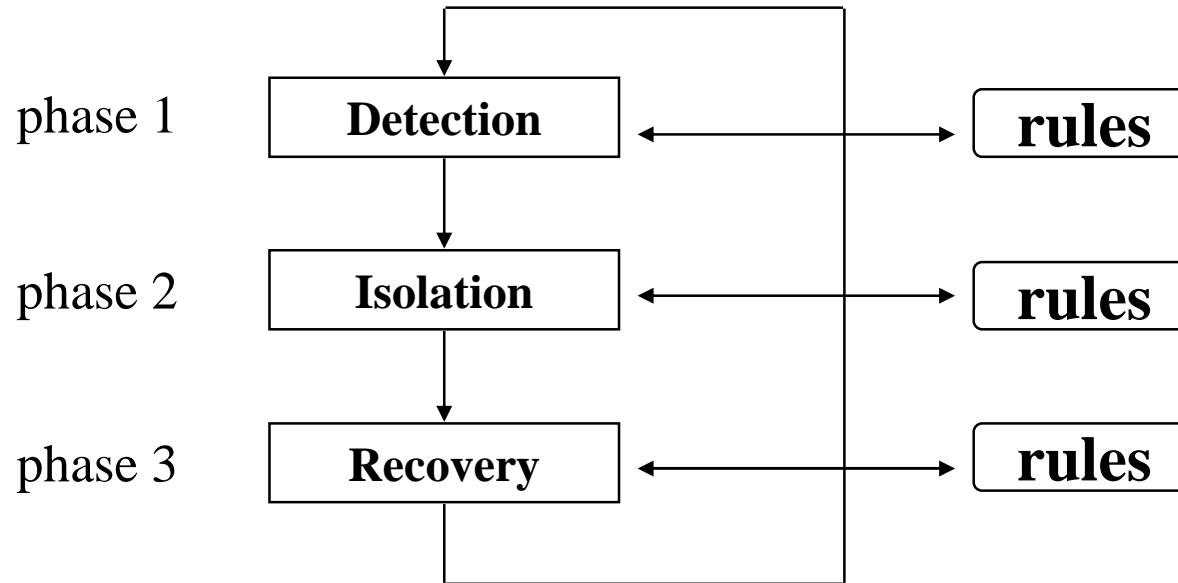


*If **pick-A** is deleted, or
new rules with higher
saliences are inserted, the
meanings may be changed.*

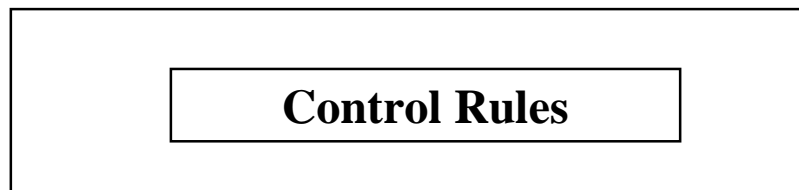


Not easy to maintain!

- Phase and Control Facts



Expert Knowledge

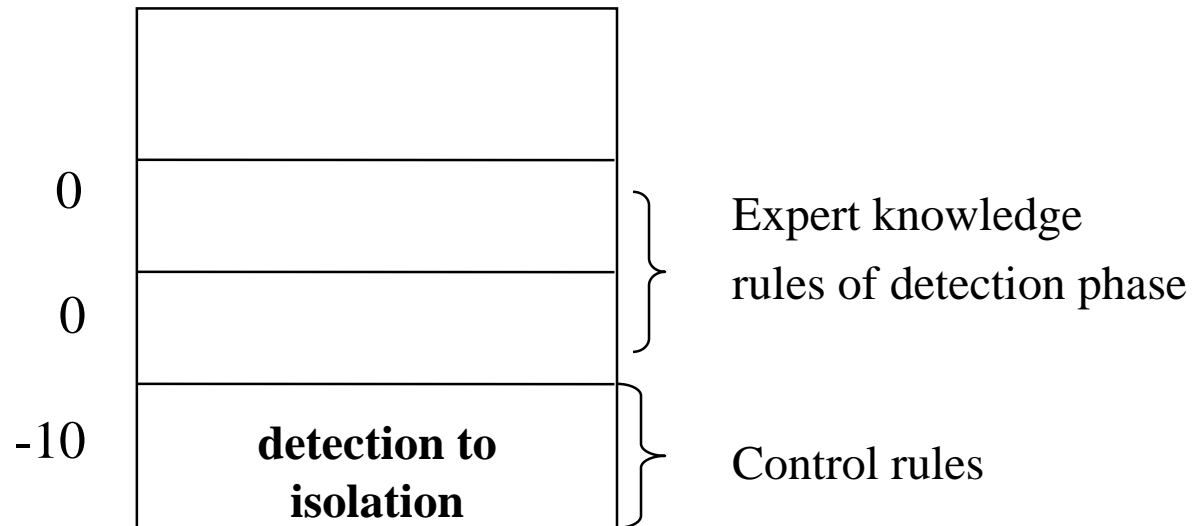


Control Knowledge

- **Control rules**

```
(defrule detection-to-isolation
  (declare (salience -10))
  ?phase <- (phase detection)
  =>
  (retract ?phase)
  (assert (phase isolation))
)
```

Fact: (phase detection)



```
(defrule isolation-to-recovery
  (declare (salience -10))
  ?phase <- (phase isolation)
  =>
  (retract ?phase)
  (assert (phase recovery))
)
```

```
(defrule recovery-to-detection
  :
  :
)
```

```
(defrule find-fault-location-and-recovery
  (phase recovery)
  (recovery-solution switch-device ?x on)
  =>
  (printout t "Switch device?" ?x "on" crlf)
)
```

Control rules

A rule of recovery phase

```
CLIPS> (assert (phase detection)) ←┘  
CLIPS> (watch rules) ←┘  
CLIPS> (run 10) ←┘
```

```
FIRE 1  detection-to-isolation : f-1  
FIRE 2  isolation-to-recovery  : f-2  
FIRE 3  recovery-to-detection  : f-3  
FIRE 4  detection-to-isolation : f- 4  
FIRE 5  isolation-to-recovery  : f-5
```

```
.  
.
```

```
FIRE 10  detection-to isolation : f-10
```

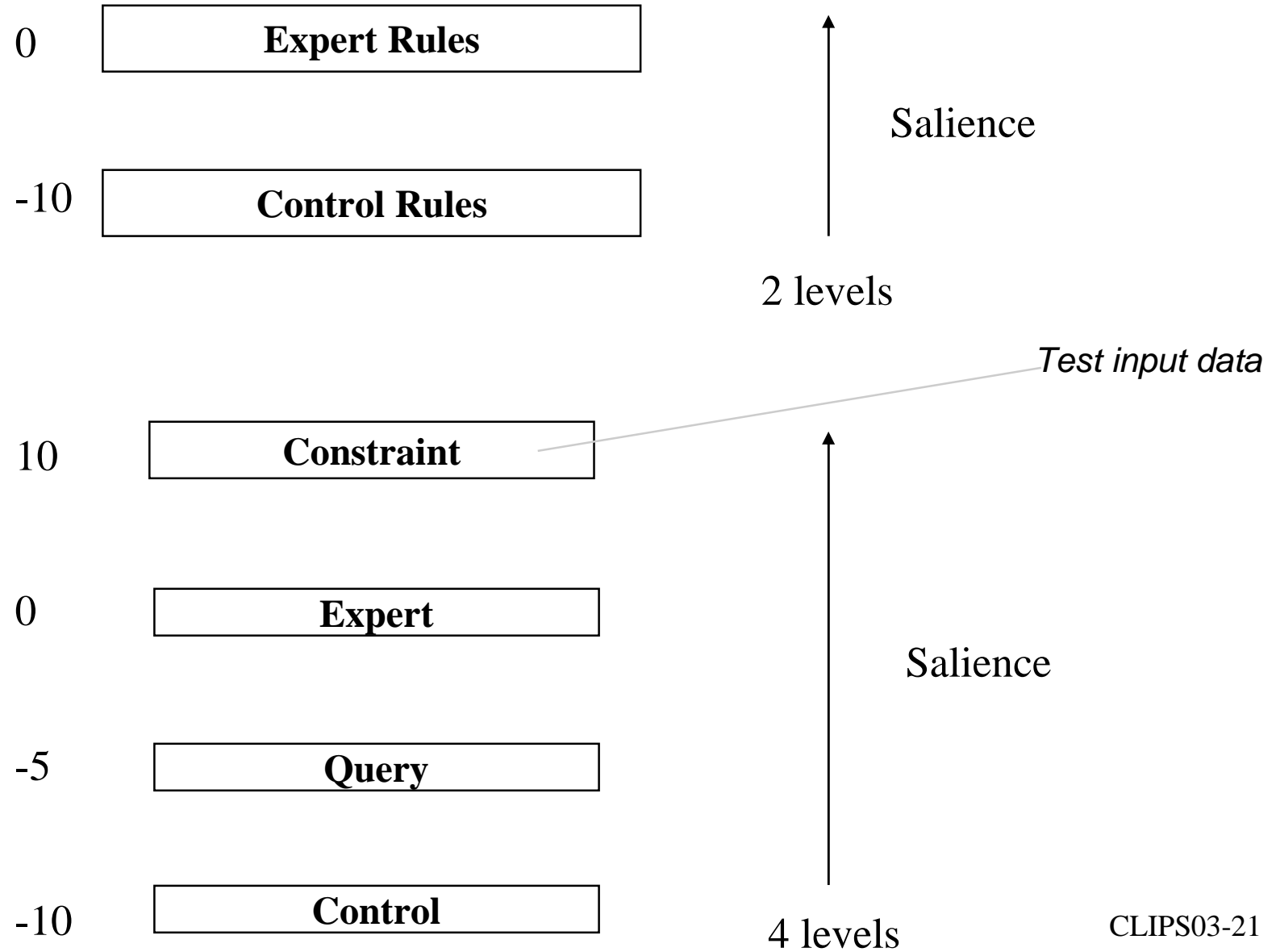
```
rule firing limit reached  
10 rules fired
```

```
CLIPS> █
```

```
(deffacts Control-Information
  (phase detection)
  (phase-after detection isolation)
  (phase-after isolation recovery)
  (phase-after recovery detection)
)
```

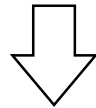
```
(defrule change-phase
  (declare (salience -10))
  ?phase <- (phase ?current-phase)
  (phase-after ?current-phase ?next)
  =>
  (retract ?phase)
  (assert (phase ?next))
)
```

- Saliency hierarchy



- Pattern Logical “OR”


```
(defrule shut-off-electricity
  (or (emergency flood)
        (fire-class C)
        (sprinkler-system active)
  )
  =>
  (printout t “Shut off the electricity” crlf)
)
```



```

AND (defrule shut-off-electricity
      (electricity-power on)
      (or (emergency flood)
           (fire-class C)
           (sprinkler-system active)
      )
      OR
      =>
      (printout t “Shut off ...” crlf)
    )
  
```

```
(defrule shut-off
  ?power <- (electricity-power on)
  (or ?reason <- (emergency flood)
      ?reason <- (fire-class C)
      ?reason <- (sprinkler-system active)
  )
=>
  (retract ?power ?reason)
  (assert (electrical-power off))
)
```

```
(defrule shut-off
  ?power <- (electrical-power on)
  (or ?reason1 <- (emergency flood)
      ?reason2 <- (fire-class C)
      ?reason3 <- (sprinkler-system active)
  )
=>
  (retract ?power ?reason1 ?reason2 ?reason3)
  (assert (electrical-power off))
)
```


- Pattern Logical “AND”

```
(defrule electrical-fire
  (emergency fire)
  (fire-class C)
  =>
  (printout t “Shut off the electricity” crlf)
)
```

||

```
(defrule electrical-fire
  (and (emergency fire))
  (fire-class C)
  )
=>
(printout t “Shut off the electricity” crlf)
)
```

(defrule shut-off-electricity

 ?power <- (electrical-power on)

 (or (emergency flood) ①

 (and (emergency fire) ②
 (fire-class C))

)

 (sprinkler-system active) ③

)

=>

(retract ?power)

(assert (electrical-power off))

(printout t "shut off the electricity" crlf)

)

```

(defrule shut-off-1
  ?power <- (electrical-power on)
  (emergency flood)
  =>                                ①
  (retract ?power)
)
(defrule shut-off-2
  ?power <- (electrical-power on)
  (emergency fire) }                ②
  (fire-class C)  }
  =>
  (retract ?power)
)
(defrule shut-off-3
  ?power <- (electrical-power on)
  (sprinkler-system active) ③
  =>
  (retract ?power)
  :
)

```

- Pattern Logical “NOT”

```
(defrule no-emergency
```

```
  (report-status)
```

```
  (not (emergency ?))
```

No such fact exists

```
=>
```

```
  (printout t “No emergency” crlf)
```

```
)
```

```
(defrule Largest-number
```

```
  (number ?x&:(numberp ?x))
```

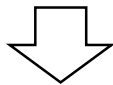
```
  (not (number ?y&:(> ?y ?x)))
```

```
=>
```

```
  (printout t “Largest number is” ?x crlf)
```

```
)
```

There does not exist some ?y, such that ?y > ?x.



?x should be the maximum value

EX. 9-5 Is the variable X referenced properly for the following rules?

1. (defrule example-1
 (not (fact ?x))
 (test (> ?x 4))
=>
 :
)
2. (defrule example-2
 (not (fact ?x &:(> ?x 4)))
=>
 :
)
3. (defrule example-3
 (not (fact ?x))
 (fact ?y &:(> ?y ?x))
=>
 :
)
4. (defrule example-4
 (not (fact ?x))
 (fact ?x &:(> ?x 4))
=>
 :
)